

ON THE LAPLACE GENERALIZED CONVOLUTION TRANSFORM

Le Xuan Huy and Nguyen Xuan Thao (Hanoi, Vietnam)

(Received February 5, 2013; accepted August 1, 2014)

Abstract. Several classes of integral transforms related to Laplace generalized convolution are studied. Necessary and sufficient conditions to ensure that the transformation is unitary are obtained, and a formula for the inverse transformation is derived in this case. In the application, we obtain solutions of several classes of integro-differential equations in closed form.

1. Introduction

Laplace transform is an integral transform method which is of the form

$$(\mathcal{L}f)(y) = \int_0^{\infty} f(x)e^{-yx}dx, \quad y > 0.$$

Here, the integral converges for functions f of the exponential order $\alpha > 0$, i.e., there exists a positive M and $x_0 \geq 0$ such that $|f(x)| \leq Me^{\alpha x}$, $x \geq x_0$. This transform finds wide applications in various terms of electrical engineering, optics, signal processing, partial different equation, integral equation, inverse problems and so on (see [3, 5, 6, 9, 10, 11, 12, 15]).

Key words and phrases: convolution, Fourier sine, Fourier cosine, Laplace, transform, integro-differential equation.

2010 Mathematics Subject Classification: 33C10, 44A35, 45E10, 45J05, 47A30, 47B15.

This research is funded by Vietnam's National Foundation for Science and Technology Development (NAFOSTED) under grant 101.02-2014.08.

<https://doi.org/10.71352/ac.43.303>

Although, so far there have been many articles about convolution transforms (see [1, 2, 4, 7, 12, 13, 14, 17]). But generalized convolution transform related to the Laplace transform has not been studied. In this paper, we introduce several generalized convolutions related to Laplace transform. Then, we study classes of integral transforms related to these generalized convolutions, which are Laplace generalized convolution transforms.

This paper consists of four sections. The first section, reflects the content of the paper. The second section, we recall several fundamental notations used in this paper. The third section, we introduce several new generalized convolutions for the Fourier sine, Fourier cosine and the Laplace transforms; as well as together with the related integral transforms. The Watson's type theorem which gives the necessary and sufficient condition to ensure that the above integral transforms are unitary. Additionally, the Plancherel's type theorem is also obtained. In the final section, as application, we obtain solutions of several classes of integro-differential equations in closed form. The research is interested in $L_2(\mathbb{R}_+)$ space and the space of functions of exponential order $\alpha > 0$.

2. Preliminaries

The Fourier cosine and Fourier sine transforms are defined as follows (see [11, 12])

$$(2.1) \quad (F_c f)(y) = \sqrt{\frac{2}{\pi}} \int_0^{\infty} f(x) \cos xy dx = \sqrt{\frac{2}{\pi}} \frac{d}{dy} \int_0^{\infty} f(x) \frac{\sin xy}{x} dx, \quad y > 0,$$

$$(2.2) \quad (F_s f)(y) = \sqrt{\frac{2}{\pi}} \int_0^{\infty} f(x) \sin xy dx = \sqrt{\frac{2}{\pi}} \frac{d}{dy} \int_0^{\infty} f(x) \frac{1 - \cos xy}{x} dx, \quad y > 0,$$

for $f \in L_1(\mathbb{R}_+)$. The second integrals in (2.1) and (2.2) are also well-defined for $f \in L_2(\mathbb{R}_+)$.

The Fourier sine and cosine generalized convolution of f and k is defined as in [11] by

$$(2.3) \quad (f *_1 k)(x) = \frac{1}{\sqrt{2\pi}} \int_0^{\infty} f(y) [k(x+y) + \text{sign}(x-y)k(|x-y|)] dy, \quad x > 0,$$

which satisfies the following factorization and Parseval's type identities (see [1])

$$(2.4) \quad F_s(f *_1 k)(y) = (F_c f)(y)(F_s k)(y), \quad \forall y > 0, \quad f, k \in L_2(\mathbb{R}_+),$$

$$(2.5) \quad (f *_1 k)(x) = F_s[(F_c f)(F_s k)](x), \quad \forall x > 0, \quad f, k \in L_2(\mathbb{R}_+).$$

The Fourier cosine and sine generalized convolution of f and k is defined as in [8] by

$$(2.6) \quad (f *_2 k)(x) = \frac{1}{\sqrt{2\pi}} \int_0^\infty f(y)[k(x+y) - \text{sign}(x-y)k(|x-y|)]dy, \quad x > 0,$$

which satisfies the following factorization and Parseval's type identities (see [2])

$$(2.7) \quad F_c(f *_2 k)(y) = (F_s f)(y)(F_s k)(y), \quad \forall y > 0, \quad f, k \in L_2(\mathbb{R}_+),$$

$$(2.8) \quad (f *_2 k)(x) = F_c[(F_s f)(F_s k)](x), \quad \forall x > 0, \quad f, k \in L_2(\mathbb{R}_+).$$

The Fourier cosine convolution of two functions f and k is defined as in [11] by

$$(f *_c k)(x) = \frac{1}{\sqrt{2\pi}} \int_0^\infty f(y)[k(x+y) + k(|x-y|)]dy, \quad x > 0,$$

which satisfies the following factorization identity

$$(2.9) \quad F_c(f *_c k)(y) = (F_c f)(y)(F_c k)(y), \quad \forall y > 0, \quad f, k \in L_2(\mathbb{R}_+).$$

The convolution of two functions f and k for the Laplace transform (see [5, 10])

$$(f *_L k)(x) = \int_0^x f(x-y)k(y)dy, \quad x > 0,$$

this convolution satisfies the factorization identity

$$(2.10) \quad \mathcal{L}(f *_L k)(y) = (\mathcal{L}f)(y)(\mathcal{L}k)(y), \quad y > 0.$$

This factorization identity holds for all functions f and k of exponential order $\alpha > 0$. Moreover, $(f *_L k)(x)$ of exponential order $\alpha > 0$ (see Theorem 2.39, p.92 in [10]).

3. The Laplace generalized convolution transform

In this section, we introduce several new generalized convolutions related to the Laplace transform and study classes related to integral transforms.

Definition 3.1. *The generalized convolutions with a weight function $\gamma(y) = \sin y$ of two functions f, k for the Fourier sine, Fourier cosine and Laplace transforms are defined by*

$$(3.1) \quad \begin{aligned} (f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(x) = & \frac{1}{2\pi} \int_0^\infty \int_0^\infty \left\{ \left[\frac{v}{v^2 + (x-1-u)^2} \pm \frac{v}{(v^2 + (x-1+u)^2)} \right] \right. \\ & \left. - \left[\frac{v}{v^2 + (x+1-u)^2} \pm \frac{v}{v^2 + (x+1+u)^2} \right] \right\} f(u)k(v)du dv, \end{aligned}$$

where $x > 0$.

Theorem 3.1. *Suppose that $f(x) \in L_2(\mathbb{R}_+)$ and $k(x)$ is a function of exponential order $\alpha > 0$. Then, the generalized convolutions $(f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}} \in L_2(\mathbb{R}_+)$ satisfy the Parseval's type identities*

$$(3.2) \quad (f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(x) = F_{\left\{ \begin{smallmatrix} s \\ c \end{smallmatrix} \right\}} \left[\pm \sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(\mathcal{L}k) \right](x), \quad \forall x > 0,$$

and the following factorization identities hold

$$(3.3) \quad F_{\left\{ \begin{smallmatrix} s \\ c \end{smallmatrix} \right\}} (f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(y) = \pm \sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y)(\mathcal{L}k)(y), \quad \forall y > 0.$$

Proof. From (3.1) and by using the formula (2.13.5) in [5]

$$\int_0^\infty e^{-\alpha x} \cos xy dx = \frac{\alpha}{\alpha^2 + y^2}, \quad \alpha > 0,$$

we get

$$\begin{aligned}
(f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(x) &= \frac{1}{2\pi} \int_0^\infty \int_0^\infty \int_0^\infty f(u)k(v)e^{-vy} \left\{ [\cos(x-1-u)y \pm \cos(x-1+u)y] \right. \\
&\quad \left. - [\cos(x+1-u)y \pm \cos(x+1+u)y] \right\} dudvdy \\
&= \pm \frac{2}{\pi} \int_0^\infty \int_0^\infty \int_0^\infty f(u)k(v)e^{-vy} \left\{ \begin{matrix} \sin xy \cdot \sin y \cdot \cos uy \\ \cos xy \cdot \sin y \cdot \sin uy \end{matrix} \right\} dudvdy \\
&= \pm \frac{2}{\pi} \int_0^\infty \left[\int_0^\infty f(u) \left\{ \begin{matrix} \cos uy \\ \sin uy \end{matrix} \right\} du \cdot \int_0^\infty k(v)e^{-vy} dv \right] \sin y \left\{ \begin{matrix} \sin xy \\ \cos xy \end{matrix} \right\} dy \\
&= \pm \sqrt{\frac{2}{\pi}} \int_0^\infty (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) (\mathcal{L}k)(y) \sin y \left\{ \begin{matrix} \sin xy \\ \cos xy \end{matrix} \right\} dy.
\end{aligned}$$

Therefore Parseval's type identities (3.2) hold. On the other hand, $(\mathcal{L}k)(y)$ vanishes at infinity and $f \in L_2(\mathbb{R}_+)$ therefore $\sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) (\mathcal{L}k)(y) \in L_2(\mathbb{R}_+)$.

Combining with (3.2) we have $(f \overset{\gamma}{*} k)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}} \in L_2(\mathbb{R}_+)$ and factorization identities (3.3) hold.

In the next part of this section, we reflect several properties of the integral transforms related to convolutions (2.3), (2.6) and generalized convolutions (3.1), namely, transformations of the form

$$\begin{aligned}
(3.4) \quad f(x) &\mapsto g(x) = (T_{k_1, k_2} f)(x) = \left(1 - \frac{d^2}{dx^2}\right) \left\{ (f \overset{\gamma}{*} k_1)_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(x) + (f \overset{*}{*}_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}} k_2)(x) \right\}, \\
&x > 0.
\end{aligned}$$

Theorem 3.2 (Watson's type theorem). *Suppose that $k_1(x)$ is a function of exponential order $\alpha > 0$ and $k_2(x) \in L_2(\mathbb{R}_+)$, then necessary and sufficient conditions to ensure that the transforms (3.4) are unitary on $L_2(\mathbb{R}_+)$ are that*

$$(3.5) \quad \left| \pm \sin y (\mathcal{L}k_1)(y) + (F_s k_2)(y) \right| = \frac{1}{1 + y^2}.$$

Moreover, the inverse transforms have the form

$$(3.6) \quad f(x) = \left(1 - \frac{d^2}{dx^2}\right) \left\{ (g \overset{\gamma}{*} \overline{k_1})_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}(x) + (g \overset{*}{*}_{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}} \overline{k_2})(x) \right\}.$$

Proof. Necessity. Assume that k_1 and k_2 satisfy conditions (3.5). We known that $h(y), yh(y), y^2h(y) \in L_2(\mathbb{R})$ if and only if $(Fh)(x), \frac{d}{dx}(Fh)(x), \frac{d^2}{dx^2}(Fh)(x) \in L_2(\mathbb{R})$ (Theorem 68, pp.92, [12]). Moreover,

$$\frac{d^2}{dx^2}(Fh)(x) = \frac{1}{\sqrt{2\pi}} \frac{d^2}{dx^2} \int_{-\infty}^{+\infty} h(y)e^{-ixy} dy = F[(-iy)^2 h(y)](x).$$

Specially, if h is an even or odd function such that $h(y), y^2h(y) \in L_2(\mathbb{R}_+)$, then the following equalities hold

$$(3.7) \quad \left(1 - \frac{d^2}{dx^2}\right) (F_{\{c\}_s} h)(x) = F_{\{c\}_s} [(1 + y^2)h(y)](x).$$

From conditions (3.5), therefore $\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y)$ are bounded, and hence $(1 + y^2)(\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))(F_{\{c\}_s} f)(y) \in L_2(\mathbb{R}_+)$. Since (3.4), by using Parsevals' type properties (2.5), (2.8), (3.2), and formula (3.7), we have

$$\begin{aligned} g(x) &= \left(1 - \frac{d^2}{dx^2}\right) F_{\{c\}_s} \left[\pm \sin y(F_{\{c\}_s} f)(y)(\mathcal{L}k_1)(y) + (F_{\{c\}_s} f)(y)(F_s k_2)(y) \right](x) \\ &= F_{\{c\}_s} \left[(1 + y^2)(\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))(F_{\{c\}_s} f)(y) \right](x). \end{aligned}$$

Therefore, the Parseval identities $\|f\|_{L_2(\mathbb{R}_+)} = \|F_{\{c\}_s} f\|_{L_2(\mathbb{R}_+)}$ and conditions (3.5) give

$$\begin{aligned} \|g\|_{L_2(\mathbb{R}_+)} &= \|(1 + y^2)(\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))(F_{\{c\}_s} f)(y)\|_{L_2(\mathbb{R}_+)} \\ &= \|(F_{\{c\}_s} f)(y)\|_{L_2(\mathbb{R}_+)} = \|f\|_{L_2(\mathbb{R}_+)}. \end{aligned}$$

It shows that the transforms (3.4) are isometric.

On the other hand, since

$$(1 + y^2)(\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))(F_{\{c\}_s} f)(y) \in L_2(\mathbb{R}_+),$$

we have

$$(F_{\{c\}_s} g)(y) = (1 + y^2)(\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))(F_{\{c\}_s} f)(y).$$

Using conditions (3.5), we have

$$(F_{\{c\}_s} f)(y) = (1 + y^2)(\pm \sin y(\overline{\mathcal{L}k_1})(y) + (F_s \overline{k_2})(y))(F_{\{c\}_s} g)(y).$$

Again, conditions (3.5) show that

$$(1 + y^2) (\pm \sin y(\mathcal{L}\overline{k_1})(y) + (F_s\overline{k_2})(y)) (F_{\{c\}_s}g)(y) \in L_2(\mathbb{R}_+).$$

By using (2.5), (2.8), (3.2), and formulas (3.7), we have

$$\begin{aligned} f(x) &= F_{\{c\}_s} \left[(1 + y^2) (\pm \sin y(\mathcal{L}\overline{k_1})(y) + (F_s\overline{k_2})(y)) (F_{\{c\}_s}g)(y) \right] \\ &= \left(1 - \frac{d^2}{dx^2} \right) F_{\{c\}_s} \left[\pm \sin y(F_{\{c\}_s}g)(y)(\mathcal{L}\overline{k_1})(y) + (F_{\{c\}_s}g)(y)(F_s\overline{k_2})(y) \right] \\ &= \left(1 - \frac{d^2}{dx^2} \right) \left\{ (g * \overline{k_1})_{\{1\}_2}(x) + (g * \overline{k_2})_{\{1\}_2}(x) \right\}. \end{aligned}$$

Thus, the transforms (3.4) are unitary on $L_2(\mathbb{R}_+)$ and the inverse transforms have the form (3.6).

Sufficiency. Assume that, the transforms (3.4) are unitary on $L_2(\mathbb{R}_+)$. Then the Parseval identities for Fourier cosine and sine transforms yield

$$\begin{aligned} \|g\|_{L_2(\mathbb{R}_+)} &= \|(1 + y^2) (\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y)) (F_{\{c\}_s}f)(y)\|_{L_2(\mathbb{R}_+)} \\ &= \|(F_{\{c\}_s}f)(y)\|_{L_2(\mathbb{R}_+)} = \|f\|_{L_2(\mathbb{R}_+)}. \end{aligned}$$

Therefore, the operators $M_\theta[f](y) = \theta(y)f(y)$, here

$$\theta(y) = (1 + y^2) (\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y))$$

are unitary on $L_2(\mathbb{R}_+)$, or equivalent, the conditions (3.5) hold.

Theorem 3.3 (Plancherel's type theorem). *We set*

$$\begin{aligned} \theta_{\{1\}_2}(x, u, v) &= \left[\frac{v}{v^2 + (x - 1 - u)^2} \pm \frac{v}{(v^2 + (x - 1 + u)^2)} \right] \\ &\quad - \left[\frac{v}{v^2 + (x + 1 - u)^2} \pm \frac{v}{v^2 + (x + 1 + u)^2} \right], \end{aligned}$$

and suppose that $k_1(x)$ is a function of exponential order $\alpha > 0$ and two times continuously differentiable, $k_2(x) \in L_2(\mathbb{R}_+)$ and two times continuously differentiable, satisfying conditions (3.5) and

$$\Theta_{\{1\}_2}(x, u, v) = \left(1 - \frac{d^2}{dx^2} \right) \theta_{\{1\}_2}(x, u, v), \quad K_2(x) = \left(1 - \frac{d^2}{dx^2} \right) k_2(x)$$

are bounded functions. Let $f \in L_2(\mathbb{R}_+)$ and for each positive integer N , set

$$\begin{aligned} g_N(x) &= \frac{1}{2\pi} \int_0^\infty \int_0^N \Theta_{\{\frac{1}{2}\}}(x, u, v) f(u) k_1(v) du dv \\ &\quad + \frac{1}{\sqrt{2\pi}} \int_0^N f(u) [K_2(x+u) \pm \text{sign}(x-u) K_2(|x-u|)] du. \end{aligned}$$

Then:

- 1) We have $g_N \in L_2(\mathbb{R}_+)$, and if $N \rightarrow \infty$ then g_N converges in $L_2(\mathbb{R}_+)$ norm to a function $g \in L_2(\mathbb{R}_+)$ with $\|g\|_{L_2(\mathbb{R}_+)} = \|f\|_{L_2(\mathbb{R}_+)}$.
- 2) Set $g^N = g \cdot \chi(0, N)$, then

$$\begin{aligned} f_N(x) &= \frac{1}{2\pi} \int_0^\infty \int_0^\infty \Theta_{\{\frac{1}{2}\}}(x, u, v) g^N(u) \overline{k_1}(v) du dv \\ &\quad + \frac{1}{\sqrt{2\pi}} \int_0^\infty g^N(u) [\overline{K_2}(x+u) \pm \text{sign}(x-u) \overline{K_2}(|x-u|)] du, \end{aligned}$$

also belong to $L_2(\mathbb{R}_+)$, and if $N \rightarrow \infty$ then f_N converges in norm to f .

Proof. Because of the definitions of f_N and g_N , these integrals are over finite intervals and therefore converge.

Set $f^N = f \cdot \chi(0, N)$, we have

$$\begin{aligned} g_N(x) &= \frac{1}{2\pi} \int_0^\infty \int_0^N \Theta_{\{\frac{1}{2}\}}(x, u, v) f(u) k_1(v) du dv \\ &\quad + \frac{1}{\sqrt{2\pi}} \int_0^N f(u) [K_2(x+u) \pm \text{sign}(x-u) K_2(|x-u|)] du \\ &= \left(1 - \frac{d^2}{dx^2}\right) \left\{ \frac{1}{2\pi} \int_0^\infty \int_0^\infty \theta_{\{\frac{1}{2}\}}(x, u, v) f^N(u) k_1(v) du dv \right. \\ &\quad \left. + \frac{1}{\sqrt{2\pi}} \int_0^\infty f^N(u) [k_2(x+u) \pm \text{sign}(x-u) k_2(|x-u|)] du \right\}. \end{aligned}$$

In view of Watson's type theorem, we conclude that $g_N \in L_2(\mathbb{R}_+)$. Let g be the transform of f under transformations (3.4), we have $\|g\|_{L_2(\mathbb{R}_+)} = \|f\|_{L_2(\mathbb{R}_+)}$,

and the reciprocal formulas (3.6) hold. We have

$$(g - g_N)(x) = \left(1 - \frac{d^2}{dx^2}\right) \left\{ \frac{1}{2\pi} \int_0^\infty \int_0^\infty \theta_{\left\{\begin{smallmatrix} 1 \\ 2 \end{smallmatrix}\right\}}(x, u, v)(f - f^N)(u)k_1(v)dudv \right. \\ \left. + \frac{1}{\sqrt{2\pi}} \int_0^\infty (f - f^N)(u) [k_2(x+u) \pm \text{sign}(x-u)k_2(|x-u|)] du \right\}.$$

By using Watson's type theorem, we get $(g - g_N)(x) \in L_2(\mathbb{R}_+)$ and

$$\|g - g_N\|_{L_2(\mathbb{R}_+)} = \|f - f^N\|_{L_2(\mathbb{R}_+)}.$$

Since $\|g - g_N\|_{L_2(\mathbb{R}_+)} \rightarrow 0$ as $N \rightarrow \infty$ then g_N converges in $L_2(\mathbb{R}_+)$ norm to $g \in L_2(\mathbb{R}_+)$.

Similarly, one can obtain the second part of the theorem.

The following example shows the existence k_1 and k_2 which satisfy conditions (3.5).

Example 1.

We choose $k_1(x) = i \sin x$ is a function of exponential order $\alpha > 0$, by using (3.2.9) in [5], we have

$$(3.8) \quad (\mathcal{L}k_1)(y) = \frac{i}{1+y^2}.$$

We choose the function $k_2(x) \in L_2(\mathbb{R}_+)$ such that

$$(3.9) \quad (F_s k_2)(y) = \frac{\cos y}{1+y^2}.$$

By using (2.2.14) in [5], we have

$$k_2(x) = F_s \left[\frac{\cos y}{1+y^2} \right] = \frac{1}{\sqrt{2\pi}} \int_0^\infty \frac{\sin y(x+1) + \sin y(x-1)}{1+y^2} dy \\ = \frac{1}{2\sqrt{2\pi}} \left[e^{-(x+1)} \overline{Ei}(x+1) - e^{(x+1)} Ei(-x-1) \right. \\ \left. + e^{-(x-1)} \overline{Ei}(x-1) - e^{(x-1)} Ei(-x+1) \right] \in L_2(\mathbb{R}_+),$$

here, for real nonzero values of x , the exponential integral $Ei(x)$ is defined as (see [5])

$$Ei(x) = \int_{-\infty}^x \frac{e^t}{t} dt.$$

When, since (3.8), (3.9), therefore conditions (3.5) are satisfied, i.e.,

$$|\pm \sin y(\mathcal{L}k_1)(y) + (F_s k_2)(y)| = \frac{1}{1+y^2}.$$

4. A class of integro-differential equations

Not many integro-differential equations can be solved in closed form. In this section, we consider the following integro-differential equations related to the transforms (3.4)

$$(4.1) \quad f(x) + \frac{d}{dx}(T_{\varphi, \psi} f)(x) = g(x), \quad x > 0.$$

Here, $\varphi(x) = (\varphi_1 *_{\mathcal{L}} \varphi_2)(x)$, φ_1 is given function of exponential order $\alpha > 0$, $\varphi_2(x) = (\sin t *_{\mathcal{L}} \sin t)(x)$ and $\psi(x) = (\operatorname{sech} t *_{\frac{1}{1}} \psi_1)(x)$, $\psi_1(x) \in L_2(\mathbb{R}_+)$. $g(x)$ is given function in $L_2(\mathbb{R}_+)$, and $f(x)$ is unknown function.

Theorem 4.1. *Suppose the following conditions hold*

$$(4.2) \quad 1 + (y + y^3)[\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)] \neq 0, \quad \forall y > 0.$$

Then equations (4.1) have unique solutions in $L_2(\mathbb{R}_+)$. Moreover, the solutions can be presented in closed form as follows

$$f(x) = g(x) - (q *_{\left\{ \begin{smallmatrix} F_c \\ 1 \end{smallmatrix} \right\}} g)(x),$$

where $q(x) \in L_2(\mathbb{R}_+)$ is defined by

$$(F_c q)(y) = \frac{(y + y^3)[\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]}{1 + (y + y^3)[\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]}.$$

Proof. The equations (4.1) can be rewritten in the form

$$(4.3) \quad f(x) + \left(\frac{d}{dx} - \frac{d^3}{dx^3} \right) [(f *_{\left\{ \begin{smallmatrix} \gamma \\ 2 \end{smallmatrix} \right\}} \varphi)(x) + (f *_{\left\{ \begin{smallmatrix} * \\ 2 \end{smallmatrix} \right\}} \psi)(x)] = g(x).$$

By using Parseval's type identities (3.2), (2.5) and (2.8), we have

$$(4.4) \quad \begin{aligned} \left(\frac{d}{dx} - \frac{d^3}{dx^3} \right) (f *_{\left\{ \begin{smallmatrix} \gamma \\ 2 \end{smallmatrix} \right\}} \varphi)(x) &= \left(\frac{d}{dx} - \frac{d^3}{dx^3} \right) F_{\left\{ \begin{smallmatrix} s \\ c \end{smallmatrix} \right\}} [(\pm \sin y F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(\mathcal{L}\varphi)](x) \\ &= F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} [(y + y^3) \sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(\mathcal{L}\varphi)](x), \end{aligned}$$

and

$$(4.5) \quad \left(\frac{d}{dx} - \frac{d^3}{dx^3} \right) (f \underset{\left\{ \begin{smallmatrix} 1 \\ 2 \end{smallmatrix} \right\}}{*} \psi)(x) = \left(\frac{d}{dx} - \frac{d^3}{dx^3} \right) F_{\left\{ \begin{smallmatrix} s \\ c \end{smallmatrix} \right\}} [(F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(F_s \psi)](x) \\ = \pm F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} [(y + y^3)(F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(F_s \psi)](x).$$

From (4.3), (4.4) and (4.5), we get

$$f(x) + F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} [(y + y^3) \sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(\mathcal{L}\varphi)](x) \pm F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} [(y + y^3)(F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(F_s \psi)](x) \\ = g(x).$$

Therefore,

$$(F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) + (y + y^3) [\sin y (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y)(\mathcal{L}\varphi)(y) \pm (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y)(F_s \psi)(y)] \\ = (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y),$$

or equivalent,

$$(4.6) \quad (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) [1 + (y + y^3) (\sin y (\mathcal{L}\varphi)(y) \pm (F_s \psi)(y))] = (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y).$$

From conditions (4.2) and (4.6), we have

$$(4.7) \quad (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) = (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y) \left[1 - \frac{(y + y^3) [\sin y (\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]}{1 + (y + y^3) [\sin y (\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]} \right].$$

On the other hand, by using (1.7) in [10] and factorization identity (2.10), we have

$$(4.8) \quad (\mathcal{L}\varphi)(y) = (\mathcal{L}\varphi_1)(y)(\mathcal{L}\varphi_2)(y) \\ = (\mathcal{L}\varphi_1)(y) \mathcal{L}(\sin t)(y) \mathcal{L}(\sin t)(y) \\ = \frac{1}{(1 + y^2)^2} (\mathcal{L}\varphi_1)(y).$$

Moreover, from formula (1.9.1) in [3]

$$F_c(\operatorname{sech} t)(y) = \sqrt{\frac{\pi}{2}} \operatorname{sech} \frac{\pi y}{2},$$

and formula (1.9.4) in [3] for $n = 1$

$$\frac{\sqrt{2\pi}}{4} (1 + y^2) \operatorname{sech} \frac{\pi y}{2} = F_c(\operatorname{sech}^3 t)(y),$$

combining with factorization identity (2.4), we have

$$(4.9) \quad (F_s \psi)(y) = F_c(\operatorname{sech} t)(y)(F_s \psi_1)(y) = \frac{2}{1+y^2} F_c(\operatorname{sech}^3 t)(y)(F_s \psi_1)(y).$$

From (4.8) and (4.9), we have

$$\begin{aligned} & (y+y^3) [\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)] \\ &= \sin y \frac{y}{1+y^2} (\mathcal{L}\varphi_1)(y) \pm 2y F_c(\operatorname{sech}^3 t)(F_s \psi_1)(y). \end{aligned}$$

Then, since by the formula (2.13.6) in [5]

$$(F_s e^{-t})(y) = \frac{y}{1+y^2},$$

and by using partial integration, we easily prove the following formula

$$y F_c(\operatorname{sech}^3 t)(y) = -3 F_s(\sinh t \operatorname{sech}^4 t)(y),$$

combining with factorization identities (3.3), (2.7), we have

$$\begin{aligned} (4.10) \quad & (y+y^3) [\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)] \\ &= \sqrt{\frac{\pi}{2}} \sin y (F_s e^{-t})(y) (\mathcal{L}\varphi_1)(y) \mp 6 F_s(\sinh t \operatorname{sech}^4 t)(F_s \psi_1)(y) \\ &= \sqrt{\frac{\pi}{2}} F_c(e^{-t} * \varphi_1)_2(y) \mp 6 F_c((\sinh t \operatorname{sech}^4 t) * \psi_1)_2(y) \\ &= F_c \left[\sqrt{\frac{\pi}{2}} (e^{-t} * \varphi_1)_2 \mp 6 (\sinh t \operatorname{sech}^4 t) * \psi_1 \right] (y) \in L_2(\mathbb{R}_+). \end{aligned}$$

From (4.10), conditions (4.2) and Wiener-Levy theorem in [16], there exists a function $q(x) \in L_2(\mathbb{R}_+)$ such that

$$(4.11) \quad (F_c q)(y) = \frac{(y+y^3) [\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]}{1+(y+y^3) [\sin y(\mathcal{L}\varphi)(y) \pm (F_s \psi)(y)]}.$$

From (4.7), (4.11) and using factorization identities (2.4), (2.9), we have

$$\begin{aligned} (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} f)(y) &= (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y) - (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y) (F_c q)(y) \\ &= (F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} g)(y) - F_{\left\{ \begin{smallmatrix} c \\ s \end{smallmatrix} \right\}} \left(q *_{\left\{ \begin{smallmatrix} F_c \\ 1 \end{smallmatrix} \right\}} g \right)(y). \end{aligned}$$

Therefore,

$$f(x) = g(x) - \left(q *_{\left\{ \begin{smallmatrix} F_c \\ 1 \end{smallmatrix} \right\}} g \right)(x), \quad f(x) \in L_2(\mathbb{R}_+).$$

The proof is complete.

References

- [1] **Al-Musallam, F. and V.K. Tuan**, A class of convolution transformations, *Fractional Calculus and Applied Analysis*, **3** (3) (2000), 303-314.
- [2] **Al-Musallam, F. and V.K. Tuan**, Integral transforms related to a generalized convolution, *Results Math.*, **38** (3-4) (2000), 197-208.
- [3] **Beteman, H. and A. Erdelyi**, *Table of Integral Transforms*, McGraw-Hill Book Company, Inc., New York - Toronto, 1954.
- [4] **Britvina, L.E.**, A class of integral transforms related to the Fourier cosine convolution, *Int. Trans. and Spec. Func.*, **16** (5-6) (2005), 379-389.
- [5] **Debnath, L. and D. Bhatta**, *Integral Transforms and Their Applications*, Chapman and Hall/CRC, Boca Raton, 2007.
- [6] **Fujiwara, T. Matsuura T., S. Saitoh and Y. Sawano**, Numerical real inversion of the Laplace transform by using a high-accuracy numerical method, *Further Progress in Analysis*, World Sci. Publ., Hackensack, NJ, 2009, 574-583.
- [7] **Hong, N.T., T. Tuan and N.X. Thao**, On the Fourier cosine-Kontorovich-Lebedev generalized convolution transforms, *Applications of Mathematics*, **58** (4) (2013), 473-486.
- [8] **Kakichev, V.A., N.X. Thao and V.K. Tuan**, On the generalized convolutions for Fourier cosine and sine transforms, *East-West Journal of Mathematics*, **1** (1) (1998), 85-90.
- [9] **Saitoh, S., V.K. Tuan and M. Yamamoto**, Reverse convolution inequalities and applications to inverse heat source problems, *J. of Ineq. in Pure and App. Math.*, **3** (5) (2002), 1-11.
- [10] **Schiff, J.L.**, *The Laplace Transforms: Theory and Applications*, Springer-Verlag New York, Inc., 1999.
- [11] **Sneddon, I.N.**, *Fourier Transforms*, McGraw-Hill, New York, 1951.
- [12] **Titchmarsh, E.C.**, *Introduction to the Theory of Fourier Integrals*, Third edition. Chelsea Publishing Co., New York, 1986.
- [13] **Thao, N.X., V.K. Tuan and N.T. Hong**, A Fourier generalized convolution transform and applications to integral equations, *Fractional Calculus and Applied Analysis*, **15** (3) (2012), 493-508.
- [14] **Tuan, V.K.**, Integral transforms of Fourier cosine convolution type, *J. Math. Anal. Appl.*, **229** (1999), 519-529.
- [15] **Tuan, V.K. and T. Tuan**, A real-variable inverse formula for the Laplace transform, *Int. Trans. and Spec. Func.*, **23** (8) (2012), 551-555.

- [16] **Volosivets, S.S.**, On weighted analogs of Wiener's and Levy's theorems for Fourier-Vilenkin series, *Izv. Saratov. Univ. Mat. Mekh. Inform.*, **11** (3) (1) (2011), 3-7.
- [17] **Yakubovich, S.B.**, Integral transforms of the Kontorovich-Lebedev convolution type, *Collect. Math.*, **54** (2) (2003), 99-110.
- [18] **Yakubovich, S.B. and A.I. Mosinski**, Integral-equation and convolutions for transform of Kontorovich-Lebedev type, *Diff. Uravnenia*, **29** (7) (1993), 1272-1284. (in Russian)

Le Xuan Huy

Faculty of Basic Science
University of Economics
and Technical Industries
456 Minh Khai
Hanoi, Vietnam
lxxhuy@uneti.edu.vn

Nguyen Xuan Thao

School of Applied
Mathematics and Informatics
Hanoi University of
Science and Technology
1 Dai Co Viet
Hanoi, Vietnam
thaonxbmai@yahoo.com