

FIX-POINT FREE AFFINE TRANSFORMATIONS HAVING INVARIANT LINES

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*Dedicated to Professors Zoltán Daróczy and Imre Kátai
on their 75th anniversary*

Communicated by Antal Járai

(Received December 07, 2012; accepted April 10, 2013)

Abstract. We extend a result of E. Kasperek characterizing continuous affine transformations without fixed points $f : X \rightarrow X$ having invariant straight line to the case when X is an arbitrary real topological linear space.

In this note X always denotes a real topological linear space and $f : X \rightarrow X$ a continuous affine transformation having no fixed point. In our considerations an important role is played by transformation $g : X \rightarrow X$ given by the formula

$$(1) \quad g(x) = f(x) - f(0) - x, \quad x \in X.$$

Note that g is a linear function transforming X into itself. We characterize transformations f in the class of functions having an invariant straight line. Our main result extends an analogous theorem obtained by Erwin Kasperek [1] who has proved it in the case $X = \mathbb{R}^n$. As usual for each nonnegative integer n by f^n we mean the n -th iterate of f , i.e., $f^0(x) = x$, $f^{n+1}(x) = f(f^n(x))$. In a similar way, in the case if f is invertible we may define the n -th iterates for arbitrary integer n . Moreover symbol \mathbb{Z} stands for the set of all integers. We start with some basic remarks.

Remark 1. *If $l \subset X$ is a straight line and $f(l) \subset l$ then $f(l) = l$.*

Key words and phrases: Affine transformations, invariant lines, function equations.
2010 Mathematics Subject Classification: 39B22, 51N20.

Proof. Assume that $f(l)$ has exactly one point $z \in l$. In particular, $f(z) = z$, which is not the case. Therefore $f(l)$ contain at least two different point u and v . Let $u = f(x)$, $v = f(y)$, $x \neq y$, $x, y \in l$. Now, affinity of f implies that

$$\lambda u + (1 - \lambda)v = f(\lambda x + (1 - \lambda)y) \in l,$$

which together with our assumption $f(l) \subset l$ proves that $f(l) = l$. ■

Remark 2. If f has an invariant straight line l then the restriction f to l , i.e., function $f|_l$ is invertible.

Proof. If $x, y \in l$, $x \neq y$ and $f(x) = f(y) = z$ then $z \in l$ and taking $\lambda \in \mathbb{R}$ such that $z = \lambda x + (1 - \lambda)y$ we get

$$f(z) = f(\lambda x + (1 - \lambda)y) = \lambda f(x) + (1 - \lambda)f(y) = z,$$

a contradiction. ■

In the reminder we use the following lemma.

Lemma 3. If l is an invariant straight line of f then $f|_l$ is a translation, i.e., there exists a $v \in X \setminus \{0\}$ such that for each $x \in l$ we have

$$(2) \quad f(x) = x + v.$$

Proof. For every $x \in l$ the points $f(x)$, $f^2(x)$ also belong to l . Thus there exists a function $\varphi : l \rightarrow \mathbb{R} \setminus \{0\}$ such that

$$(3) \quad \varphi(x)[f(x) - x] = f^2(x) - f(x), \quad x \in l.$$

We shall show that for each $x \in l$ we have $\varphi(x) = 1$. Firstly, we observe that $\varphi(x) \neq -1$. In fact, the condition $\varphi(x) = -1$ implies that $f^2(x) = x$ and consequently,

$$f\left(\frac{x + f(x)}{2}\right) = \frac{f(x) + f^2(x)}{2} = \frac{f(x) + x}{2},$$

which means that f has a fixed-point, a contradiction. Let's rewrite (3) to the following form

$$f(x) = \frac{\varphi(x)}{1 + \varphi(x)}x + \frac{1}{1 + \varphi(x)}f^2(x).$$

It follows from affinity of f that

$$f^2(x) = \frac{\varphi(x)}{1 + \varphi(x)}f(x) + \frac{1}{1 + \varphi(x)}f^3(x),$$

which is equivalent to the following condition

$$\varphi(x)[f^2(x) - f(x)] = f^3(x) - f^2(x).$$

Hence and by (3) we infer that

$$\varphi(x) = \varphi(f(x)),$$

and, consequently,

$$(4) \quad \varphi(f^n(x)) = \varphi(x),$$

for all integer n . By virtue of (3) and (4) we obtain

$$\varphi(x)^{k+1}(f(x) - x) = f^{k+2}(x) - f^{k+1}(x), \quad k \in \mathbb{Z},$$

whence

$$(5) \quad \sum_{k=0}^n \varphi(x)^{k+1}(f(x) - x) = f^{n+2}(x) - f(x), \quad n \in \mathbb{Z}.$$

Assume now that $\varphi(x) \neq 1$. Then (5) has a form

$$(6) \quad \varphi(x) \frac{1 - \varphi(x)^{n+1}}{1 - \varphi(x)} (f(x) - x) = f^{n+2}(x) - f(x).$$

If $|\varphi(x)| < 1$, then we tend with n to infinity, and if $|\varphi(x)| > 1$, we tend with n to minus infinity. In both cases the sequence $f^n(x)$ is convergent. It is easy to see that its limit point has to be a fixed-point of f . This shows that

$$\varphi(x) = 1, \quad x \in l.$$

According to (3) we get

$$(7) \quad f(x) - x = f^{k+1}(x) - f^k(x), \quad x \in l, \quad k \in \mathbb{Z}.$$

Let us fix $x, y \in l$. Chose an integer k and $\lambda \in \mathbb{R}$ such that

$$y = \lambda f^k(x) + (1 - \lambda) f^{k+1}(x).$$

Then

$$f(y) = \lambda f^{k+1}(x) + (1 - \lambda) f^{k+2}(x),$$

and using also (7)

$$\begin{aligned} f(y) - y &= \lambda(f^{k+1}(x) - f^k(x)) + (1 - \lambda)(f^{k+2}(x) - f^{k+1}(x)) \\ &= \lambda(f(x) - x) + (1 - \lambda)(f(x) - x) = f(x) - x. \end{aligned}$$

Setting $v := f(y) - y$ we obtain $v \neq 0$ and

$$f(x) = x + v, \quad x \in l.$$

This ends the proof of Lemma 3. ■

Lemma 4. *If f has an invariant straight line and g is defined by (1) then $f(0) = u + v$, where $u \in \text{Im } g$, $v \in \ker g \setminus \{0\}$.*

Proof. Let l be an invariant straight line of f . On account of Lemma 3

$$f(x) = x + v, \quad x \in l,$$

where v is a fixed nonzero vector of X . For each $x \in l$ we have $x + v \in l$. Therefore $f(x) = x + v$ and $f(x + v) = x + v + v$, whence $f(x + v) - f(0) - (f(x) - f(0)) = v$, $x \in l$. By linearity of $f - f(0)$ on X we get

$$f(v) - f(0) = v.$$

Finally, $g(v) = 0$, which means that $v \in \ker g$. Setting $u := f(0) - v$ and taking an $x \in l$ we get

$$g(-x) = -g(x) = -f(x) + x + f(0) = -v + f(0) = u,$$

whence $u \in \text{Im } g$, and the proof of Lemma 4 is complete. ■

Lemma 5. *If $f(0) = u + v$, where $u \in \text{Im } g$ and $v \in \ker g \setminus \{0\}$ then f has an invariant straight line.*

Proof. By our assumptions

$$(8) \quad f(v) - v - f(0) = 0$$

and $-u \in \text{Im } g$. Let $x_1 \in X$ be such that

$$(9) \quad f(x_1) - x_1 - f(0) = -u.$$

Let us put

$$H := \{x \in X; f(x) = x + v\}.$$

According to (9) we get

$$f(x_1) = x_1 + f(0) - u = x_1 + v,$$

whence $x_1 \in H$. Moreover, by the linearity of $f - f(0)$ and (8) we get

$$\begin{aligned} f(x_1 + v) &= f(x_1 + v) - f(0) + f(0) = f(x_1) - f(0) + f(v) = \\ &= x_1 + v - f(0) + v + f(0) = x_1 + v + v, \end{aligned}$$

whence $x_1 + v \in H$. Therefore H contains at least two different points. Let l be the straight line generated by this points. For an arbitrary $w \in l$ there exists a $\lambda \in \mathbb{R}$ such that $w = \lambda x_1 + (1 - \lambda)(x_1 + v)$. Then

$$\begin{aligned} f(w) &= f(\lambda x_1 + (1 - \lambda)(x_1 + v)) = \lambda f(x_1) + (1 - \lambda)f(x_1 + v) = \\ &= \lambda(x_1 + v) + (1 - \lambda)(x_1 + 2v) = x_1 + (2 - \lambda)v = \\ &= (\lambda - 1)x_1 + (2 - \lambda)(x_1 + v). \end{aligned}$$

This means that $f(l) \subset l$ and now our assertion follows from Remark 1. \blacksquare

From Lemmas 4 and 5 the following theorem easy follows.

Theorem 6. *Transformation f has an invariant straight line if and only if there exist a $u \in \text{Im } g$ and $v \in \text{ker } g \setminus \{0\}$ such that $f(0) = u + v$.*

Corollary 7. *Transformation f has an invariant straight line if and only if $g(f(0)) \in \text{Im } g^2$.*

Proof. If f has an invariant straight line then on account of Lemma 2 $f(0) = u + v$, where $u \in \text{Im } g$ and $v \in \text{ker } g \setminus \{0\}$. Therefore $g(f(0)) = g(u) \in \text{Im } g^2$. On the other hand, if $g(f(0)) \in \text{Im } g^2$ then there exists a $w \in X$ such that $g(f(0)) = g(g(w))$. Therefore $g(f(0) - g(w)) = 0$, and hence $f(0) - g(w) = v$, where $v \in \text{ker } g$. To end the proof it is enough to show that $v \neq 0$. Suppose $v = 0$. Then $f(0) = g(w)$ and according to (1)

$$-g(w) = g(-w) = f(-w) + w - f(0),$$

or equivalently,

$$f(-w) = -w,$$

a contradiction. \blacksquare

Corollary 8. *If g transforms X onto X and $g^2 = g$ then f has an invariant straight line.*

Proof. It follows from our assumptions that

$$X = \text{ker } g \oplus \text{Im } g.$$

Thus $f(0) = v + u$, where $v \in \text{ker } g$ and $u \in \text{Im } g$. Moreover $v \neq 0$ because otherwise f would have a fixed point. Now, it is enough to apply Theorem 6. \blacksquare

References

- [1] **Kasperek, E.**, The invariant straight lines of an affine transformation in \mathbb{R}^n without fixed points, *Ann. Math. Sil.*, **24** (2010), 35–37.

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