

DEGENERATE CENTER IN A PREDATOR-PREY SYSTEM WITH MEMORY

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Abstract. The purpose of this paper is to establish the occurrence of a degenerate center in a predator-prey system with memory due to Farkas et al [2], and described by a system of two differential equations with continuous delay. This study is done showing that the Liapunov coefficients of the system are null, by using a theorem due to Liapunov (see [1]). Finally, we construct a computer program for the calculation of these coefficients of similar problems.

1. Introduction

In this work we shall establish the occurrence of a degenerate center in a predator-prey system introduced in [2]. The model is described by a two-dimensional system

$$(1) \quad \begin{aligned} \dot{N}(t) &= \epsilon N(t) \left(1 - \frac{N(t)}{K} - \frac{P(t)\alpha}{\epsilon} \right), \\ \dot{P}(t) &= -\gamma P(t) + \beta P(t) \int_{-\infty}^t N(\tau) G(t - \tau) d\tau, \end{aligned}$$

where the parameters in (1) are all non-negative and represent

- $N(t)$: quantity of prey,
- $P(t)$: quantity of predator,
- ϵ : specific growth rate of prey,
- α : predation rate,
- γ : mortality of predator,
- β : conversion rate of the prey,
- K : carrying capacity of the environment,
- $G(s) = ae^{-as}$: density function.

The introduction of the notation

$$(2) \quad Q(t) = a \int_{-\infty}^t N(\tau) e^{-a(t-\tau)} d\tau$$

transforms (1) into

$$(3) \quad \begin{aligned} \dot{N} &= \epsilon N \left(1 - \frac{N}{K} - \frac{P\alpha}{\epsilon} \right), \\ \dot{P} &= -\gamma P + \beta PQ, \\ \dot{Q} &= a(N - Q), \end{aligned}$$

where the last equation was obtained differentiating (2); we shall study (3) with $t \in [0, \infty)$ and $N, P, Q \geq 0$. The change of variables $N = Kn$, $P = Kp$, $Q = Kq$ and the introduction of the new time $t = \frac{s}{\epsilon}$, transforms (3) into

$$(4) \quad \begin{aligned} \frac{dn}{ds} &= n(1-n) - \frac{npK\alpha}{\epsilon}, \\ \frac{dp}{ds} &= -\frac{\gamma p}{\epsilon} + \frac{pqK\beta}{\epsilon}, \\ \frac{dq}{ds} &= \frac{a(n-q)}{\epsilon}. \end{aligned}$$

Farkas et al (see [2]) proved the occurrence of an Andronov-Hopf bifurcation in (3), restricting (4) to the two-dimensional center manifold to obtain

$$\dot{x} = \omega y + W \left\{ -\epsilon(1-\gamma b)x^2 - \epsilon(1-\gamma b) \left[\left(\frac{\gamma b}{\omega} \right)^2 - \frac{\gamma b(1-\gamma b)}{\omega^2 \epsilon b} \right] y^2 + \right.$$

$$\begin{aligned}
 & +xy \left(1 - 2\gamma b - 2\epsilon\gamma b^2\right) \frac{1 - \gamma b}{\omega b} \Big\} + \\
 & + Wh(x, y) \left\{ \left[-2\epsilon \left(\frac{\gamma b}{\omega}\right)^2 - \epsilon + 2\epsilon\gamma b \left(\frac{\gamma b}{\omega}\right)^2 + 2\epsilon\gamma b \right] x + \right. \\
 & \left. + y \left[1 - 2\epsilon b \left(\frac{\gamma b}{\omega}\right)^2 - \epsilon b + \gamma b \frac{1 - \gamma b(1 - \gamma b)\gamma}{\omega^2} \right] \right\}, \\
 \dot{y} = & -\omega x + W \left\{ -\omega\epsilon^2 b x^2 - \omega\epsilon^2 b \left[\left(\frac{\gamma b}{\omega}\right)^2 - \gamma b \frac{1 - \gamma b}{\epsilon b \omega^2} \right] y^2 + \right. \\
 (5) \quad & \left. + \left[\frac{(1 - \gamma b) \left(1 + \left(\frac{\gamma b}{\omega}\right)^2 + \epsilon b\right)}{b} - 2\epsilon^2 \gamma b^2 \right] xy \right\} + \\
 & + Wh(x, y) \left\{ - \left[2 \left(\frac{\gamma b}{\omega}\right)^2 \epsilon b + \epsilon b + 1 + \left(\frac{\gamma b}{\omega}\right)^2 \right] \omega \epsilon x - \right. \\
 & \left. - \omega\epsilon^2 b \left[2 \left(\frac{\gamma b}{\omega}\right)^3 + \frac{\gamma b}{\omega} - \left(\frac{\gamma b}{\omega}\right)^2 \frac{1 - \gamma b}{b\omega\epsilon} + \frac{1 - \gamma b}{b^2\omega\epsilon^2} + \left(\frac{\gamma b}{\omega}\right)^2 \frac{1 - \gamma b}{b^2\omega\epsilon^2} \right] y \right\},
 \end{aligned}$$

where $b = \frac{1}{K\beta}$, $\omega = \left(\frac{(1 - \gamma b - \gamma\epsilon b^2)}{\epsilon}\right)^{\frac{1}{2}}$. With the introduction of the new parameters

$$(6) \quad u = \frac{\epsilon}{\gamma}, \quad v = \frac{K\beta}{\gamma}, \quad w = \frac{\gamma}{a}$$

the situation was considered in the three-dimensional parameter space u, v, w and the following surface F of bifurcation was obtained

$$(7) \quad w(v^2 - v - u) - v = 0.$$

In [2] it was proved that when this surface is crossed, an Andronov-Hopf bifurcation occurs. It is supercritical (resp. subcritical) if the crossing is below or above the curve g , whose equation is

$$(8) \quad 2v - 1 - \left(\frac{8u^2 + 9u + 2}{u + 2}\right)^{\frac{1}{2}} = 0.$$

In Section 2, we shall present some phase portrait executed with the software PHASER, whereby the occurrence of a degenerate center becomes apparent.

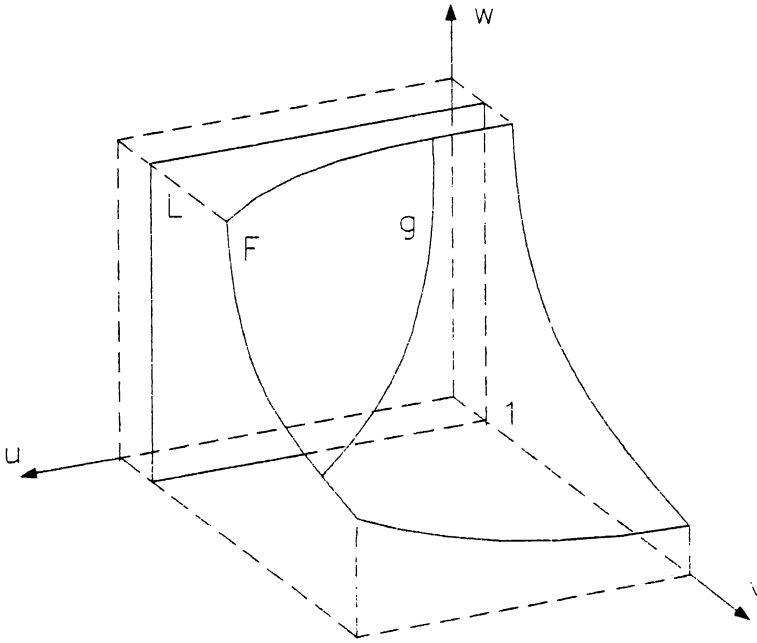


Figure 1. Bifurcation surface

In Section 3, we shall describe an algorithm establishing the Proposition.

Finally, we shall give a program to calculate the Liapunov coefficients.

We are to choose now parameter values on the curve g that divides the bifurcation surface into two, a supercritical and a subcritical part. At these values the bifurcation shall be degenerate, neither supercritical, nor subcritical. The aim of the present paper is to show the character of this bifurcation.

Proposition 1.1. *System (5) with the parameters*

$$(9) \quad \begin{aligned} K = 0.7, \quad \epsilon = 0.424264, \quad \gamma = 0.3, \quad \alpha = 0.5, \quad \beta = 0.85714, \\ a = 0.087868, \quad b = 1.666666389 \end{aligned}$$

admits a formal first integral of the form

$$F(x, y) = x^2 + y^2 + \sum_{k=3}^{\infty} F_k(x, y),$$

here $F_k(x, y) = \sum_{j=1}^{k+1} A_{kj} x^{k+1-j} y^{j-1}$ is a homogeneous polynomial of degree k , $k = 3, 4, 5, \dots$, $j = 1, 2, \dots, k + 1$.

As a consequence of Proposition 1.1, the system (3) admits a local center around the origin.

2. Simulations

From equation (8) $v = \frac{1}{2} \left(1 + \sqrt{\frac{8u^2 + 9u + 2}{u + 2}} \right)$; taking $u = 1$ we get $v = \frac{1}{2} \left(1 + \frac{\sqrt{57}}{3} \right)$. Replacing the values of u and v in (7) we obtained $w = \frac{1}{2} (3 + \sqrt{57})$. Substituting u, v, w in (6) we get

$$\epsilon = \gamma, \quad \beta = \frac{\gamma}{2K} \left(1 + \frac{\sqrt{57}}{3} \right), \quad a = \frac{2\gamma}{3 + \sqrt{57}}.$$

The parameters given in (9) determine a point on g . Considering these values in system (4) and the initial conditions

$$\begin{aligned} (n_1, p_1, q_1) &= (0.7, 0.7, 0.7); & (n_2, p_2, q_2) &= (0.6, 0.6, 0.6); \\ (n_3, p_3, q_3) &= (0.5, 0.5, 0.5); & (n_4, p_4, q_4) &= (0.4, 0.4, 0.4); \\ (n_5, p_5, q_5) &= (0.2, 0.2, 0.2), \end{aligned}$$

we present the following simulations, generated by the software PHASER. This suggests the existence of degenerate center.

In the simulation we consider $t = 0..100$ (Figure 1(a)) and $t = 0..500$ (Figure 1(b)). One can see that the center has a limit.

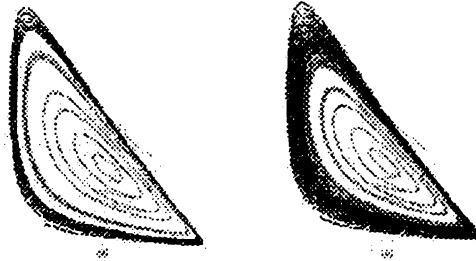


Figure 2. Local center

3. The algorithm

System (5) with the parameters (9) takes the form

$$\begin{aligned}
 \dot{x} &= 0.321797436y - 0.2426410358x^2 + 0.2426410357y^2 - \\
 &\quad - 0.7540176237xy + 0.5308179897x^3 + 0.4538306270x^2y - \\
 &\quad - 0.4397447763xy^2 - 0.1708148734y^3, \\
 \dot{y} &= -0.321797436x - 0.1104235269x^2 + 0.1104235267y^2 + \\
 &\quad + 1.071068092xy + 0.53381710952x^3 + 1.002761197x^2y - \\
 &\quad - 0.1500939754xy^2 - 0.7184908404y^3.
 \end{aligned}
 \tag{10}$$

Liapunov's theorem [1] implies that the formal series

$$F(x, y) = x^2 + y^2 + \sum_{k=3}^{\infty} F_k(x, y),
 \tag{11}$$

where $F_k(x, y) = A_{k1}x^k + A_{k2}x^{k-1}y + \dots + A_{kk}xy^{k-1} + A_{k,k+1}y^k$, can be determined such that $F'_{10}(x, y) = G_{2k}(x^2 + y^2)^k + o((x^2 + y^2)^k)$, with $k = 1, 2, \dots$. Here $F'_{10}(x, y)$ means the differentiation of F with respect to the system (10) and G_{2k} are the Liapunov coefficients for the equilibrium $(0, 0)$ of (10). It can be proven that, if $G_{2k} = 0$, $k = 1, 2, \dots$ then $(0, 0)$ is a local center and the system admits a first integral of the form (11). To achieve this objective, we shall construct an algorithm to determine these coefficients and $G_{2k} = 0$.

Adding the homogeneous polynomials $F_3(x, y)$ and $F_4(x, y)$ to $F_2(x, y) = x^2 + y^2$ we obtain $F_{2,3,4}(x, y) = x^2 + y^2 + \sum_{j=1}^4 A_{3j}x^{4-j}y^{j-1} + \sum_{j=1}^5 A_{4j}x^{5-j}y^{j-1}$, with undetermined coefficients A_{3j} , $j = 1, \dots, 4$ and A_{4j} , $j = 1, \dots, 5$. To determine these coefficients, we calculate the derivative of $F_{2,3,4}(x, y)$ with respect to (10) and equal the coefficients from the terms of third and fourth order and the coefficients of the polynomial $G_4(x^2 + y^2)^2 = G_4x^4 + 2G_4x^2y^2 + G_4y^4$ to obtain the following system of linear equations:

$$\begin{aligned}
 &0.3217974364A_{33} + 0.2208470534 = 0 \\
 &0.4852820716 - 0.3217974364A_{32} = 0 \\
 (12) \quad &-1.7288823 - 0.6435948728A_{33} + 0.9653923092A_{31} = 0 \\
 &-0.9653923092A_{34} + 2.627418255 + 0.6435948728A_{32} = 0 \\
 &0.3312705801A_{34} + 0.3217974364A_{44} + 0.2426410356A_{33} - \\
 &\quad -1.436981681 = G_4 \\
 &-0.3217974364A_{42} - 0.1104235269A_{32} - 0.7279231074A_{31} + \\
 &\quad +1.061635979 = G_4 \\
 &0.7279231068A_{31} + 0.9653923092A_{42} + 1.899495148A_{33} - \\
 &-1.397611720A_{32} - 0.9653923092A_{44} - 0.3312705807A_{34} + \\
 &\quad +1.126032843 = 2G_4 \\
 &1.287189746A_{41} - 2.262052870A_{31} + 0.5857860204A_{32} - \\
 &\quad -0.6435948728A_{43} - 0.2208470538A_{33} + 1.974003446 = 0 \\
 &-1.287189746A_{45} - 0.5331705699A_{33} + 0.4852820712A_{32} + \\
 &\quad +3.213204276A_{34} + 0.6435948728A_{43} - 0.6418176996 = 0.
 \end{aligned}$$

Solving the first four equations we find

$$\begin{aligned}
 A_{31} &= 1.333331725, & A_{32} &= -1.508035853, \\
 A_{33} &= -0.6862921466, & A_{34} &= 1.716249545.
 \end{aligned}$$

Substituting the values found for A_{3j} , $j = 1, \dots, 4$ into (12) the fifth, sixth and seventh equations can be solved independently of A_{41} , A_{43} and A_{45} and we get

$$A_{42} = 0.8004917008, \quad A_{44} = 3.216187222, \quad G_4 = -0.5330875000 \times 10^{-6}.$$

We may consider $G_4 = 0$.

To find $G_6 = 0$, we need to determine the constants A_{41} , A_{43} and A_{45} . To achieve this, we add $F_5(x, y) = \sum_{j=1}^6 A_{5j}x^{6-j}y^{j-1}$ to $F_{2,3,4}(x, y)$, we calculate the derivative with respect to (10) and we equal the coefficients from the terms of fifth order to zero to obtain a system of six equations with indeterminate coefficients A_{4j} , $j = 1, 3, 5$ and A_{5j} $j = 1, \dots, 6$. Grouping these equations with the last two in (12), we get

$$\begin{aligned}
 & 1.287189746A_{41} - 1.773884131 - 0.6435948728A_{43} = 0 \\
 & -1.287189746A_{45} + 4.506930690 + 0.6435948728A_{43} = 0 \\
 & 1.230835152 - 0.9705641432A_{41} - 0.3217974364A_{52} = 0 \\
 & -2.801720830 + 0.3217974365A_{55} + 0.4416941068A_{45} = 0 \\
 & -1.608987182A_{56} + 0.6435948730A_{54} + 0.4852820714A_{43} + \\
 & \quad + 4.284272368A_{45} - 0.329257256 = 0 \\
 & 1.608987183A_{51} - 3.016070495A_{43} - 0.6435948728A_{53} - \\
 & \quad - 0.2208470538A_{43} - 1.755002194 = 0 \\
 & 1.287189746A_{52} + 1.656854112A_{43} + 0.9705641428A_{41} - \\
 & \quad - 0.9653923092A_{54} - 4.684711778 = 0 \\
 & 0.9653923095A_{53} - 1.287188194A_{43} - 1.287189746A_{55} - \\
 & \quad - 0.4416941076A_{43} + 16.92065858 = 0.
 \end{aligned}$$

Solving the previous system, in terms of A_{45} , we obtain

$$\begin{aligned}
 A_{41} &= -2.123266258 + 0.9999999997A_{45}; \\
 A_{43} &= 2A_{45} - 7.002744862; \\
 A_{51} &= -9.952764969 + 2.666663451A_{45}; \\
 A_{52} &= 10.22879885 - 3.016071706A_{45}; \\
 A_{53} &= 1.294079159A_{45} - 15.25558638; \\
 A_{54} &= -5.367351123 + 0.4164273838A_{45}; \\
 A_{55} &= 8.706473428 - 1.372584293A_{45}; \\
 A_{56} &= -4.463654858 + 3.432499091A_{45}.
 \end{aligned}$$

We must give A_{45} a value such that, $G_6 = 0$ and the terms of third order of $F'_{2,3,4}(x, y)_{(10)}$ be null. To achieve these results, we add $F_6(x, y) =$

$= \sum_{j=1}^7 A_{6j}x^{7-j}y^{j-1}$ to $F_{2,3,4,5}(x, y)$, we substitute $A_{41}, A_{43}, A_{51}, A_{52}, A_{53}, A_{54}, A_{55}, A_{56}$ depending of A_{45} , we calculate the derivative with respect to (10) and we equal the coefficients of the terms of sixth order in both sides of

$$G_6(x^2 + y_2)^3 = G_6x^6 + 3G_6x^4y^2 + 3G_6x^2y^4 + G_6y^6$$

to obtain a system of seven equations with the constants indeterminate A_{45} and A_{6j} , $j = 1, \dots, 7$:

(13)

$$\begin{aligned} 6.863773295 - 0.778892676A_{45} - 0.3217974364A_{62} &= G_6 \\ -0.901287442 - 1.311865361A_{45} + 0.3217974365A_{66} &= G_6 \\ 19.82531980A_{45} - 76.95710798 - 0.9653923092A_{64} + 1.608987183A_{62} &= 3G_6 \\ -7.612567551A_{45} + 48.68689632 + 0.9653923095A_{64} - 1.608987182A_{66} &= 3G_6 \\ -1.930784618A_{67} + 17.72934095A_{45} - 35.18266588 + 0.6435948730A_{65} &= 0 \\ 32.67569982 - 6.694469985A_{45} - 0.6435948728A_{63} + 1.930784619A_{61} &= 0 \\ -1.162157565A_{45} + 29.52817523 + 1.287189746A_{63} - 1.287189746A_{65} &= 0. \end{aligned}$$

The first four equations in (13) can be solved in terms of A_{45} independently of the constants A_{61}, A_{63}, A_{65} and A_{67} , and $G_6 = 0$ if

$$A_{45} = -0.8767770729;$$

consequently:

$$\begin{aligned} A_{41} &= -3.000043331; & A_{43} &= -8.756299008; & A_{45} &= -0.8767770729; \\ A_{51} &= -12.29083434; & A_{52} &= 12.87322137; & A_{53} &= -16.39020532; \\ A_{54} &= -5.732465106; & A_{55} &= 9.909923867; & A_{56} &= -7.473191364; \\ A_{62} &= 23.45167388; & A_{64} &= 58.63528289; & A_{66} &= -0.773548826. \end{aligned}$$

There are some constants to determine: A_{61}, A_{63}, A_{65} and A_{67} . Observe that, to obtain $G_6 = 0$ we solved a system of seven equations in terms of A_{45} , where the first four equations could be solved independently of the constants in the last three equations, and after we give an adequate value to A_{45} .

We may generalize the idea, i.e. for $k = 1, 2, \dots$ we can obtain $G_{2k} = 0$ solving a system with $2k + 1$ equations attributing an adequate value to $A_{2k-2, 2k-1}$. This follows.

Once $G_{2k-2} = 0$ has been determined by equating the terms of order $2k - 2$ in both sides of $F'_{2,\dots,2k-2}(x, y) = G_{2k-2}(x^2 + y^2)^{\frac{2k-2}{2}}$ and giving a value to $A_{2k-4,2k-3}$, we also find the values of the constants $A_{2k-4,j}$, $j = 1, 3, \dots, 2k - 5$, $A_{2k-3,j}$, $j = 1, 2, \dots, 2k - 2$ and $A_{2k-2,j}$, $j = 2, 4, \dots, 2k - 2$, we have $A_{2k-2,j}$, $j = 1, 3, \dots, 2k - 1$ to determine. To do this, we add

$$F_{2k}(x, y) = \sum_{j=1}^{2k+1} A_{2k,j} x^{2k+1-j} y^{j-1} \text{ to } F_{2,\dots,2k-1}(x, y) \text{ and find}$$

$$F_{2,\dots,2k}(x, y) = x^2 + y^2 + \sum_{j=1}^4 A_{3j} x^{4-j} y^{j-1} + \dots + \sum_{j=1}^{2k+1} A_{2k,j} x^{2k+1-j} y^{j-1}.$$

We substitute the values of $A_{2k-4,j}$, $j = 1, 2, \dots, 2k - 3$, $A_{2k-3,j}$, $j = 1, 2, \dots, 2k - 2$ and $A_{2k-2,j}$, $j = 2, 4, \dots, 2k - 2$; then we calculate $F'_{2,\dots,2k-1}(x, y)$ and equate the coefficients of the **term of third order** of $F'_{2,\dots,2k-1}(x, y)$ to zero to obtain a system of $2k$ equations with undetermined coefficients **given previously**. In this system we solve $A_{2k-2,j}$, $j = 1, 3, \dots, 2k - 3$ and $A_{2k-1,j}$, $j = 1, 2, \dots, 2k$ in terms of $A_{2k-2,2k-1}$. To conclude add

$$F_{2k}(x, y) = \sum_{j=1}^{2k+1} A_{2k,j} x^{2k+1-j} y^{j-1}$$

to $F_{2,\dots,2k-1}(x, y)$ and find

$$F_{2,\dots,2k}(x, y) = x^2 + y^2 + \sum_{j=1}^4 A_{3j} x^{4-j} y^{j-1} + \dots + \sum_{j=1}^{2k+1} A_{2k,j} x^{2k+1-j} y^{j-1}.$$

We substitute the constants depending of $A_{2k-2,2k-1}$ into $F_{2,\dots,2k}(x, y)$ and calculate $F'_{2,\dots,2k}(x, y)$; equating the coefficients of the terms of order $2k$ in both sides of the equation $F'_{2,\dots,2k}(x, y) = G_{2k}(x^2 + y^2)^{\frac{2k}{2}}$ we determine a system of $2k + 1$ equations depending on the constants $A_{2k-2,2k-1}$ and $A_{2k,j}$, $j = 1, \dots, 2k + 1$. The first $k + 1$ equations depend on $A_{2k-2,2k-1}$, G_{2k} and $A_{2k,j}$, $j = 2, 4, \dots, 2k$ and can be solved independently of $A_{2k,j}$, $j = 1, 3, \dots, 2k + 1$. Solving these equations in terms of $A_{2k-2,2k-1}$ we obtain G_{2k} depending on $A_{2k-2,2k-1}$. Attributing a value to $A_{2k-2,2k-1}$ such that $G_{2k} = 0$, we find also the constants that we were to determine in the two previous steps, $A_{2k-2,j}$, $j = 1, 3, \dots, 2k - 3$, $A_{2k-1,j}$, $j = 1, 2, \dots, 2k$ and $A_{2k,j}$, $j = 2, 4, \dots, 2k$. We are to determine $A_{2k,j}$, $j = 1, 3, \dots, 2k + 1$, so that $G_{2k+2} = 0$.

In this way we determine $G_{2k} = 0$, $k = 1, 2, \dots$. Then system (10) admits a formal first integral and, consequently, a local center around origin.

4. The program

In this section, we give a program realized with MAPLE-VIII which computes the Liapunov coefficients for the system (10) and for similar systems.

```

restart; n := 12:
w := 0.3217974364 : a1 := -0.2426410358 : b1 := -0.7540176233 :
c1 := 0.2426410356 : d1 := 0.5308179897 : e1 := 0.4538306273 :
f1 := -0.4397447761 : g1 := -0.1708148739 : a2 := -0.1104235269 :
b2 := 1.071068092 : c2 := 0.1104235267 : d2 := 0.5331710957 :
e2 := 1.002761197 : f2 := -0.1500939759 : g2 := -0.7184908406 :
x1 := w * y(t) + a1 * x(t)^2 + b1 * x(t) * y(t) + c1 * y(t)^2 + d1 * x(t)^3 +
    e1 * x(t)^2 * y(t) + f1 * x(t) * y(t)^2 + g2 * y(t)^3 :
y1 := -w * x(t) + a2 * y(t) + a2 * x(t)^2 + b2 * x(t) * y(t) + c2 * y(t)^2 + d2 * x(t)^3 +
    e2 * x(t)^2 * y(t) + f2 * x(t) * y(t)^2 + g2 * y(t)^3 :
for i from 3 by 1 to n do
    F[i](t) := (sum(A[i,j] * x(t)^(i+1-j) * y(t)^(j-1), j=1..i+1));
    if irem(i,2)=0 then
        GK[i](t) := G[i] * (x(t)^2 + y(t)^2)^(i/2);
    else
    end if:
end do:
for i from 3 by 1 to n do
    Eqs[i] := :
    if irem(i,2)=0 then
        a[i] := seq(A[i,j], j=0..i): A[i,0] := G[i]:
        else a[i] := seq(A[i,j], j=1..i+1):
    end if:
end do:
F(t) := x(t)^2 + y(t)^2:
for l from 3 by 1 to n do
    F(t) := F(t) + F[l](t):

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FP(t):=(subs(diff(x(t),t)=x1,diff(y(t),t)=y1,diff(F(t),t))):
for i from 0 by 1 to 1 do
  for j from 0 by 1 to 1 do
    if i+1>=3 then
      EqFP[i,j]:=coeff(coeff(FP(t),y(t),j),x(t),i)=
        coeff(coeff(GK[i+j](t),y(t),j),x(t),i):
    else
      end if:
    end do:
  end do:
for k from 3 by 1 to 1 do
  for i from 0 by 1 to 1 do
    for j from 0 by 1 to 1 do
      if k=i+j then
        Eqs[k]:=Eqs[k] union EqFP[i,j]:
      else
        end if:
      end do:
    end do:
  end do:
for i from 3 by 1 to 1 1 do
  if irem(i,2)=0 and i<>4 then
    assign(solvefor[a[i]](Eqs[i])):
    assign(solvefor[A[i-2,i-1]](G[i]=0)):
  else
    assign(solvefor[a[i]](Eqs[i])):
  end if:
end do:
end do:
unassign('i','j','k','l'):
GG:=seq(G[2*i],i=2..n/2):
for i from 3 by 1 to n-1 do
  FL[i]:=(sum(A[i,j]*x^(i+1-j)*y^(j-1), j=1..i+1)):
end do:
FLT:=x^2+y^2+(sum(FL[k],k=3..n-1)):
print("The Liapunov coefficients", 'G[4]', 'G[6]', " ... ", 'G[n]' "are:" ,):

```

```
print(GG):  
# print("The first integral is:")  
# print(FLT):
```

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