

SPLINE APPROXIMATIONS FOR A SYSTEM OF ORDINARY DIFFERENTIAL EQUATIONS. II

TH. FAWZY* and Z. RAMADAN**

* Dept. of Math., Fac. of Science, Suez Canal Univ., Ismailia, Egypt

** Dept. of Math., Fac. of Education, Ain Shams Univ., Cairo, Egypt

(Received May 23, 1985)

Abstract. In this paper we present a method for approximating the solution of the system of nonlinear ordinary differential equations $y' = f_1(x, y, z)$, $z' = f_2(x, y, z)$ with $y(x_0) = y_0$ and $z(x_0) = z_0$ adopting spline functions which are not necessarily polynomial splines. It is a one-step method $O(h^{2+\alpha})$ in $y(x)$, $y'(x)$, $y''(x)$, $z(x)$, $z'(x)$ and $z''(x)$ where $0 < \alpha \leq 1$, assuming that $f_1, f_2 \in C^1[a, b]$.

Description of the method

Consider the system of ordinary differential equations

$$(1) \quad y' = f_1(x, y, z), \quad y(x_0) = y_0,$$

$$(2) \quad z' = f_2(x, y, z), \quad z(x_0) = z_0,$$

where $f_1, f_2 \in C^1([0, 1] \times \mathbb{R}^2)$.

Let Δ be the partition

$$\Delta: 0 = x_0 < x_1 < \dots < x_k < x_{k+1} < \dots < x_n = 1,$$

where $x_{k+1} - x_k = h$ and $k = 0, 1, \dots, n-1$.

Let L_1 and L_2 be the Lipschitz constants satisfied by the functions f_1, f_1' and f_2, f_2' respectively, i.e.,

$$(3) \quad |f_1^{(j)}(x, y_1, z_1) - f_1^{(j)}(x, y_2, z_2)| \leq L_1\{|y_1 - y_2| + |z_1 - z_2|\}, \quad j = 0, 1$$

and

$$(4) \quad |f_2^{(j)}(x, y_1, z_1) - f_2^{(j)}(x, y_2, z_2)| \leq L_2\{|y_1 - y_2| + |z_1 - z_2|\}, \quad j = 0, 1$$

for all (x, y_1, z_1) and (x, y_2, z_2) in the domain of definition of f_1, f_1', f_2 and f_2' .

Then we define the spline functions approximating $y(x)$ and $z(x)$ by $S_\Delta(x)$ and $\bar{S}_\Delta(x)$ by:

$$(5) \quad S_\Delta(x) = S_k(x), \quad x_k \leq x \leq x_{k+1}, \quad k = 0, 1, \dots, n-1$$

and

$$(6) \quad \bar{S}_\Delta(x) = \bar{S}_k(x), \quad x_k \leq x \leq x_{k+1}, \quad k = 0, 1, \dots, n-1.$$

Both $S_\Delta(x)$ and $\bar{S}_\Delta(x)$ are given by

$$(7) \quad S_k(x) = S_{k-1}(x_k) + \int_{x_k}^x f_1[t, y_k^*(t), z_k^*(t)] dt, \quad k = 0, 1, \dots, n-1,$$

where

$$(8) \quad \begin{aligned} y_k^*(t) &= S_{k-1}(x_k) + f_1\{x_k, S_{k-1}(x_k), \bar{S}_{k-1}(x_k)\}(t - x_k) + \\ &+ \frac{1}{2} f_1'\{x_k, S_{k-1}(x_k), \bar{S}_{k-1}(x_k)\}(t - x_k)^2, \end{aligned}$$

$$(9) \quad \begin{aligned} z_k^*(t) &= \bar{S}_{k-1}(x_k) + f_2\{x_k, S_{k-1}(x_k), \bar{S}_{k-1}(x_k)\}(t - x_k) + \\ &+ \frac{1}{2} f_2'\{x_k, S_{k-1}(x_k), \bar{S}_{k-1}(x_k)\}(t - x_k)^2, \quad x_k \leq t \leq x_{k+1}, \end{aligned}$$

$$(10) \quad S_{-1}(x_0) = y_0, \quad \bar{S}_{-1}(x_0) = z_0$$

and

$$(11) \quad \bar{S}_k(x) = \bar{S}_{k-1}(x_k) + \int_{x_k}^x f_2[t, y_k^*(t), z_k^*(t)] dt.$$

It is clear by the construction, that $S_\Delta(x)$ and $\bar{S}_\Delta(x) \in C[0, 1]$.

It should be noted that we use the Lipschitz conditions on f_1 and f_2 to guarantee the existence of a unique solution to the problem (1)–(2).

We now discuss the convergence of these approximants.

For all $x \in [x_k, x_{k+1}]$, $k = 0, 1, \dots, n-1$ the exact solutions of (1) and (2) can be written – by using Taylor's expansion – in the forms:

$$(12) \quad y(x) = y_k + \int_{x_k}^x f_1[t, y_k(t), z_k(t)] dt,$$

where

$$(13) \quad y_k(t) = y_k + y_k'(t - x_k) + \frac{1}{2} y_k''(\xi_k)(t - x_k)^2,$$

$$(14) \quad z_k(t) = z_k + z_k'(t - x_k) + \frac{1}{2} z_k''(\eta_k)(t - x_k)^2,$$

$$\xi_k, \eta_k \in (x_k, x_{k+1})$$

and

$$(15) \quad z(x) = z_k + \int_{x_k}^x f_2[t, y_k(t), z_k(t)] dt.$$

We now estimate $|y(x) - s_0(x)|$ where $x \in [x_0, x_1]$.

Using (7–10), (12–14) and the Lipschitz condition (3), we get

$$(16) \quad \begin{aligned} |y(x) - s_0(x)| &\leq \int_{x_0}^x |f_1[t, y_0(t), z_0(t)] - f_1[t, y_0^*(t), z_0^*(t)]| dt \leq \\ &\leq L_1 \int_{x_0}^x \{|y_0(t) - y_0^*(t)| + |z_0(t) - z_0^*(t)|\} dt. \end{aligned}$$

Now let

$$U = |y_0(t) - y_0^*(t)| \text{ and } v = |z_0(t) - z_0^*(t)|.$$

Then

$$(17) \quad U = \frac{1}{2} |y''(\xi_0) - y_0''| |t - x_0|^2$$

and

$$(18) \quad V = \frac{1}{2} |z''(\eta_0) - z_0''| |t - x_0|^2.$$

Thus using (16), (17) and (18) we get:

$$(19) \quad |y(x) - s_0(x)| \leq \frac{h^3}{6} L_1 \{\omega(y'', h) + \omega(z'', h)\} \leq \frac{1}{3} L_1 h^3 \omega(h) = O(h^{3+\alpha}),$$

where $\omega(y'', h)$ and $\omega(z'', h)$ are the moduli of continuity of the functions y'' and z'' respectively, and

$$(20) \quad \omega(h) = \max \{\omega(y'', h), \omega(z'', h)\}.$$

We now estimate $|y'(x) - z'(x)|$.

Using (7–10), (12–14) and the Lipschitz condition (3) we get

$$(21) \quad \begin{aligned} |y'(x) - s_0'(x)| &\leq \frac{1}{2} L_1 \{|y''(\xi_0) - y_0''| + |z''(\eta_0) - z_0''|\} |x - x_0|^2 \leq \\ &\leq \frac{1}{2} L_1 \{\omega(y'', h) + \omega(z'', h)\} h^2 \leq \\ &\leq L_1 h^2 \omega(h) = O(h^{2+\alpha}). \end{aligned}$$

We also estimate $|y''(x) - s_0''(x)|$. Thus using (7–10), (12–14) and the Lipschitz condition (3) we get

$$(22) \quad |y''(x) - s_0''(x)| \leq \frac{1}{2} L_1 \{ |y''(\xi_0) - y_0''| + |z''(\eta_0) - z_0''| \} |x - x_0|^2 \leq \\ \leq L_1 h^2 \omega(h) = O(h^{2+\alpha}).$$

By the same way, using (8–11), (13–15) and employing the Lipschitz condition (4), it can be shown that

$$(23) \quad |z(x) - \bar{s}_0(x)| \leq \frac{1}{3} L_2 h^3 \omega(h) = O(h^{3+\alpha}),$$

$$(24) \quad |z'(x)_0' - \bar{s}_0(x)| \leq L_2 h^2 \omega(h) = O(h^{2+\alpha}),$$

and

$$(25) \quad |z''(x) - \bar{s}_0''(x)| \leq L_2 h^2 \omega(h) = O(h^{2+\alpha}).$$

Now, we are going to consider the general subinterval $[x_k, x_{k+1}]$, $k = 1, 2, \dots, n-1$.

Using (7–9), (12–14) and the Lipschitz condition (3), we get

$$(26) \quad |y(x) - s_k(x)| \leq |y_k - s_{k-1}(x_k)| + L_1 \int_{x_k}^x \{ |y_k(t) - y_k^*(t)| + |z_k(t) - z_k^*(t)| \} dt.$$

Now let

$$U_1 = |y_k(t) - y_k^*(t)|.$$

Then

$$(27) \quad U_1 \leq |y_k - s_{k-1}(x_k)| + |y_k' - f_1\{x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)\}| |t - x_k| + \\ + \frac{1}{2} |y''(\xi_k) - f_1'\{x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)\}| |t - x_k|^2.$$

Using the fact that $s_d(x) \in C[0, 1]$, $\bar{s}_d(x) \in C[0, 1]$ and the notations

$$e(x) = |y(x) - s_k(x)|, \\ e_k(x) = |y_k - s_k(x_k)|, \\ \bar{e}(x) = |z(x) - \bar{s}_k(x)|, \\ \bar{e}_k(x) = |z_k - \bar{s}_k(x_k)|,$$

and if we let

$$T = |y_k' - f_1\{x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)\}|,$$

then

$$T \leq L_1 \{ |y_k - s_{k-1}(x_k)| + |z_k - \bar{s}_{k-1}(x_k)| \},$$

i. e.

$$(29) \quad T \leq L_1(e_k + \bar{e}_k),$$

and if we let

$$T_1 = |y''(\xi_k) - f'_1\{x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)\}|,$$

then

$$T_1 \leq |y''(\xi_k) - y_k''| + |f'_1(x_k, y_k, z_k) - f'_1\{x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)\}|,$$

i. e.

$$(30) \quad T_1 \leq \omega(y'', h) + L_1(e_k + \bar{e}_k).$$

Now, using (28–30) in the inequality (27), we get

$$(31) \quad U_1 \leq e_k + L_1(e_k + \bar{e}_k)|t - x_k| + \frac{1}{2}\{\omega(y'', h) + L_1(e_k + \bar{e}_k)\}|t - x_k|^2.$$

Similarly, let

$$V_1 = |z_k(t) - z_k^*(t)|.$$

Then, using (28) and the Lipschitz condition (4), we get

$$(32) \quad V_1 \leq \bar{e}_k + L_2(e_k + \bar{e}_k)|t - x_k| + \frac{1}{2}\{\omega(z'', h) + L_2(e_k + \bar{e}_k)\}|t - x_k|^2.$$

Using (26), (28), (31) and (32) we can easily get

$$(33) \quad e(x) \leq e_k(1 + c_0h) + c_0h\bar{e}_k + \frac{1}{3}L_1h^3\omega(h),$$

where $c_0 = L_1 + \frac{2}{3}L_1^2 + \frac{2}{3}L_1L_2$ is a constant independent of h and $h < 1$.

Similarly using (13–15), (8, 9, 11) and the Lipschitz conditions (3–4) we can easily see that

$$(34) \quad \bar{e}(x) \leq \bar{e}_k(1 + c_1h) + c_1he_k + \frac{1}{3}L_2h^3\omega(h),$$

where $c_1 = L_2 + \frac{2}{3}L_2^2 + \frac{2}{3}L_1L_2$ is a constant independent of h and $h < 1$.

If we use the matrix notations

$$E(x) = (e(x) \bar{e}(x))^T,$$

$$E_k = (e_k \bar{e}_k)^T, \quad k = 0, 1, \dots, n-1,$$

then the estimations (33) and (34) can be written in the form

$$E(x) \leq \begin{pmatrix} 1 + c_0h & c_0h \\ c_1h & 1 + c_1h \end{pmatrix} E_k + \frac{1}{3}h^3\omega(h) \begin{pmatrix} L_1 \\ L_2 \end{pmatrix},$$

i. e.

$$(35) \quad E(x) \leq (I + hA)E_k + \frac{1}{3}h^3\omega(h)B,$$

where

$$A = \begin{pmatrix} c_0 & c_0 \\ c_1 & c_1 \end{pmatrix}, \quad B = \begin{pmatrix} L_1 \\ L_2 \end{pmatrix}$$

and I is the identity matrix of order 2.

At this point, we use the following definition of the matrix norm. Let $\tau = [t_{ij}]$ be an $m \times n$ matrix, then we define

$$\|\tau\| = \max_i \sum_{j=1}^n |t_{ij}|.$$

Using this definition, we get

$$(36) \quad \|E_k\| = \max(e_k, \bar{e}_k), \quad k = 0, 1, \dots, n-1.$$

Now, since (35) is valid for all $x \in [x_k, x_{k+1}]$, $k = 0, 1, \dots, n-1$, the following inequalities hold:

$$\|E(x)\| \leq (1 + h\|A\|)\|E_k\| + \frac{1}{3}h^3\omega(h)\|B\|,$$

$$(1 + h\|A\|)\|E_k\| \leq (1 + h\|A\|)^2\|E_{k-1}\| + \frac{1}{3}h^3\omega(h)(1 + h\|A\|)\|B\|,$$

$$(1 + h\|A\|)^2\|E_{k-1}\| \leq (1 + h\|A\|)^3\|E_{k-2}\| + \frac{1}{3}h^3\omega(h)(1 + h\|A\|)^2\|B\|,$$

...

$$(1 + h\|A\|)^k\|E_1\| \leq (1 + h\|A\|)^{k+1}\|E_0\| + \frac{1}{3}h^3\omega(h)(1 + h\|A\|)^k\|B\|.$$

Adding L.H.S. and R.H.S. in these inequalities and noting that $e_0 = 0$ we get

$$(37) \quad E(x) \leq c_2 h^2 \omega(h),$$

where $c_2 = \frac{e^{\|A\|}}{3} \frac{\|B\|}{\|A\|}$ is a constant independent of h and $h < 1$.

By the definition (36), it follows that

$$(38) \quad e(x) \leq c_2 h^2 \omega(h) = O(h^{2+\alpha})$$

and

$$(39) \quad \bar{e}(x) \leq c_2 h^2 \omega(h) = O(h^{2+\alpha}).$$

We now estimate $|y'(x) - s'_k(x)|$. For this purpose we use equations (7-9), (12-14) and the Lipschitz conditions (3-4) and get

$$(40) \quad e'(x) = |y'(x) - s'_k(x)| \leq c_3(e_k + \bar{e}_k) + L_1 h^2 \omega(h),$$

where $c_3 = \frac{3}{2}L_1^2 + \frac{3}{2}L_1L_2 + L_1$ is a constant independent of h and $h < 1$.

Using (38) and (39) inequality (40) becomes

$$(41) \quad e'(x) \leq c_4 h^2 \omega(h) = O(h^{2+\alpha}),$$

where $c_4 = 2c_2c_3 + L_1$ is a constant independent of n and $h < 1$.

In a similar manner we estimate $|z'(x) - \bar{s}'_k(x)|$.

From equations (8–11), (13–15) and using the Lipschitz conditions (3–4) it follows that

$$(42) \quad \bar{e}'(x) = |z'(x) - \bar{s}'_k(x)| \leq c_5(e_k + e_k) + L_2 h^2 \omega(h),$$

where $c_5 = \frac{3}{2}L_2^2 + \frac{3}{2}L_1L_2 + L_2$ is a constant independent of h and $h < 1$.

Substituting inequalities (38) and (39) into inequality (42) we get:

$$(43) \quad \bar{s}'(x) \leq c_6 h^2 \omega(h) = O(h^{2+\alpha}),$$

where $c_6 = 2c_2c_5 + L_2$ is a constant independent of h and $h < 1$.

We are going to estimate $|y''(x) - s''_k(x)|$ and $|z''(x) - \bar{s}''_k(x)|$, where we are using the following definitions for $s''_k(x)$ and $\bar{s}''_k(x)$:

$$(44) \quad s''_k(x) = f'_1\{x, s_k(x), \bar{s}_k(x)\}$$

and

$$(45) \quad \bar{s}''_k(x) = f'_2\{x, s_k(x), \bar{s}_k(x)\}.$$

Now, using (1) and (44) we get

$$e''(x) \equiv |y''(x) - s''_k(x)| = |f'_1(x, y, z) - f'_1(x, s_k(x); \bar{s}_k(x))|.$$

Using (38) and (39) we get

$$(46) \quad e''(x) \leq c_7 h^2 \omega(h) = O(h^{2+\alpha}),$$

where $c_7 = 2L_1c_2$ is a constant independent of h and $h < 1$.

Similarly, it can be shown that

$$(47) \quad \bar{e}''(x) \equiv |z''(x) - \bar{s}''_k(x)| \leq c_8 h^2 \omega(h) = O(h^{2+\alpha}),$$

where $c_8 = 2L_2c_2$ is a constant independent of h and $h < 1$.

Thus, we have proved the following

Theorem. Let $s_d(x)$ and $\bar{s}_d(x)$ be the approximate solutions to problem (1)–(2) given by equations (5–11), and let $f_1, f_2 \in C^1([x_0, x_n] \times \mathbb{R}^2)$. Then, for all $x \in [x_0, x_1]$ we have

$$|y(x) - s_0(x)| \leq \frac{1}{3}L_1 h^3 \omega(h),$$

$$|y^{(j)}(x) - s_0^{(j)}(x)| \leq L_1 h^2 \omega(h), \quad j = 1, 2,$$

$$|z(x) - s^*(x)| \leq \frac{1}{3} L_2 h^2 \omega(h)$$

and

$$|z^{(j)}(x) - \bar{s}_0^{(j)}(x)| \leq L_2 h^2 \omega(h), \quad j = 1, 2,$$

and for all $x \in [x_k, x_{k+1}]$, $k = 1(1)n - 1$ we have

$$|y^{(j)}(x) - \bar{s}_k^{(j)}(x)| \leq c_9 h^2 \omega(h)$$

and

$$|z^{(j)}(x) - \bar{s}_k^{(j)}(x)| \leq c_{10} h^2 \omega(h),$$

where $j = 0, 1$ and 2 , $c_9 = \max(c_2, c_4, c_7)$ and $c_{10} = \max(c_2, c_6, c_8)$.

Numerical example

Consider the following system of differential equations

$$y' = y + z - x - x^2 - e^{2x},$$

$$z' = 2y + 2z - 2e^x - 2x^2 - 2, \quad y(0) = 1, \quad z(0) = 2.$$

The method is tested using this example, in the interval $[0, 1]$ with step size $h = 0.1$.

The analytical solution is

$$y(x) = e^x + x$$

and

$$z(x) = e^{2x} + x^2 + 1.$$

The tabulated results, appearing in the following table, are evaluated at the point $x = 0.25$.

	exact value	approximate value	absolute error
y	1.5340254	1.533906117	0.000119283
y'	2.284025329	2.283397416	0.000627913
y''	1.284025155	1.282951722	0.001073433
z	2.7112212	2.710982672	0.000238528
z'	3.797442367	3.796186541	0.001255826
z''	8.594884559	8.59273769	0.002146869

REFERENCES

- [1] *Micula G.*: Spline functions of higher degree of approximation for solutions of systems of differential equations. *Studia Univ. Babeş–Bolyai, Ser. Math-Mech.* **17** (1) (1972), 21 – 32.
- [2] *Schumaker L. L.*: Optimal spline solutions of systems of ordinary differential equations. In: *Lecture Notes in Math.*, **957**. Springer, Berlin – New York, 1982, 272 – 283.